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AB ■ Abstract (summary) Translate

An early control methodology for time delayed plants is the Smith predictor, in which the plant model is utilized to predict the non-delayed output of the plant and move the delay out of the control loop. Recent Smith predictor based teleoperation control architectures have used linear or fixed-parameter dynamic approximations of the slave/environment at the master for environment contact prediction. This paper discusses and analyzes the performance of the previous work and proposes new architectures to overcome their shortcomings...

□ Indexing (details) ☐ Cite

SU. SUBT Subject Mathematical models;

> Smith predictors; Power plants; Neural networks: Nonlinear dynamics;

ΤI Title Smith Predictor Type Control Architectures for Time Delayed

Teleoperation

AU, AUFN, AULN Author Smith, Andrew C1; Hashtrudi-Zaad, Keyvan

> AF Robotics and Computer Vision Laboratory, Department of Electrical

> > and Computer Engineering, Queen's University, Walter Light Hall,

Kingston, Ontario, Canada

English LA Language

DTYPE Document type Journal Article

PUB Publication title International Journal of Robotics Research

PD, YR **Publication date** 1 Aug. 2006

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Technologies and Engineering (AN); Computer & Information Systems

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DOI http://dx.doi.org/10.1177/0278364906068393 DOL

NR Number of references DREV Date revised 2007-07-01

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FAV First available 2010-04-30

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Field Name	Field Code	Example	Description and Notes
Abstract	AB	ab("smith predictor")	Use adjacency and/or Boolean operators to narrow search results.
Abstract present	ABANY	"teleoperation control architectures" AND abany(yes)	Add: AND ABANY(YES) to a query to limit retrieval to records with abstracts.
Accession number	AN	an(200707-53-420841)	A unique document identification number assigned by the information provider. A record can display multiple accession numbers – depending on the products within which it is stored.
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All fields + text		"machine learning algorithm*"	Same as ALL field code: searches all fields in bibliographic files.
Author ¹ Author First Name Author Last Name	AU AUFN AULN	au("hashtrudi, k*") aufn(jack) auln(baker)	Includes all authors. See also First author.
First author	FAU	fau("smith, a*")	First name listed in Author field. It is included in Author browse, but its position cannot be specified in the Author browse.
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Cited publication date ²	CYR, REF	cyr(2009)	
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Conference information	CF	cf(international P/2 aeronautics) cf(glasgow) cf(sweden) cf(2008)	
Date revised	DREV	drev(>20070331)	Date that the Information Provider revised the record.
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Field Name	Field Code	Example	Description and Notes
DOI	DOI	doi(doi.org/10.1177/027836 4906068393)	Digital Object Identifier
Document feature	DF	df(graphs)	Indicates presence in original article of availability of graphics, tabular data, illustrations, etc.
Document title	TI	ti("Constraint-Based System for Genomic Analysis")	Includes Alternate (OTI), but not Publication title (PUB).
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From database ³	FDB	fdb(advancetechaeroprof) ti("jet propulsion") AND	Useful in multi-file searches to isolate records from a single file. FDB cannot be searched on its own; specify at least one search term then AND it with FDB.
ICDN	ISBN	fdb(10000195)	
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ISSN	ISSN	issn(0278-3649)	
Issue	ISS	issn(02783649) iss(8)	Hyphens are optional. Also searchable via the Look Up Citation tool.
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Language	LA	la(english)	published.
Notes	NT	nt(reprint*)	
Page count	PCT	pct(22)	
Pagination	PG	pg(797-818)	See also Start page.
Patent application number	PA, PAT	pa("09/523128")	Displayed in Patent information field.
Patent application date	PAD	pad(20101201) pad(2010-12-01) pad(>20101231) pad(20110101-20110630)	Displayed in <i>Patent information</i> field. Date range searching is supported.
Patent application number	PA, PAT	pa("d/372,641")	Displayed in Patent information field.
Patent assignee	AP, PAT	ap(boeing)	Displayed in Patent information field.
Patent publication country	PC, PAT	pc(us)	Displayed in Patent information field.
Patent publication number	PN, PAT	pn(d638085) pn(us d638085)	Displayed in Patent information field.
Publication date	PD	pd(20120726)	Also searchable via the Look Up Citation tool.

Field Name	Field Code	Example	Description and Notes
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		pd(>20120630)	
		pd(20120701-20120831)	
Publication title ¹	PUB	pub.exact("International Journal of Information and Education Technology")	Title of publication where document originally appeared. Also searchable via the Look Up Citation tool.
Publication type	PT, STYPE	pt("scholarly journals")	
Publication year	YR, PY	yr(2012) yr(>2011) yr(2011-2012)	Single year or a range of years may be searched. Displayed in <i>Publication date</i> field.
Publisher	PB	pb("sage science")	
References	REF	ref("patent citation analysis")	
Source type	PT,STYPE	pt("conference papers & proceedings")	Searches references cited in the original document.
Start page	PAGE	page(797)	Also searchable on the Look Up Citation page. Displays in Pagination.
Subfile	SFL	sfl("Electronics and Communications Abstracts")	The individual database(s) in which the record appears.
		sfl(ea)	Also searchable using two-letter codes.
Subject	SU	su("mathematica models")	Descriptor terms describing the subject matter of the original record.
		su(delay)	<u> </u>
Main subject ¹	SUBT	subt("neural networks")	SUBT searches terms from the <i>Subject</i> display field only.
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